Asian Resonance Analysis of Redundant system reliability model consisting of two active units

Abstract

This paper deals with a two-unit active (Parallel) redundant system model with two types of repair Ist and IInd. Whenever a unit fails it requires inspection to decide whether the failed unit needs type I repair or type II repair. Inspection time, type-I repair time, type-II repair time and post repair time distributions are also negative exponential. Various measures of system effectiveness are obtained by using regenerative point technique.

Keywords: Transitional Probability, exponential distribution, busyperiod, parallel unit, MTSF

Introduction

Reliability is both a desirable as well necessary factor in the modern world for achieving for positive economic growth of a nation. It is not a discipline to study for scientist and academicians but also an interesting field to the engineers, manufacturers, economists and government leaders as well. Reliability considerations make more effective use of resources. A lot of work has been reported in the literature of reliability of operating units with repairman. Various researchers including Dhillon(1978), Chung (1980, 81), Goel(1983), Wang(2004), and Mittal et.al(2006) with different types of repair have widely been studied in literature. They analysed a single unit multi-component system model with two types of repair (minor and overhaul) where the decision about the type of repair was taken by inspection. The purpose of this paper is to analyse a two-unit active (parallel) redundant system. Both the units of the system have two modes - Normal (N) and total failure (F). The system breaks down when both the units enter into F-mode whenever a unit fails it first inspected by the repairman who decides the needed type of repair (Type I or Type II) and then accordingly the repair of the failed unit is started. On completion of the repair, the unit is finally checked and re-repaired if required by the repairman. The failure and repair times of a unit are assumed to be independent and uncorrelated random variables. The distribution of time to failure of a unit is taken to be exponential.

By using regenerative point technique, the following economic measures of system effectiveness are obtained –

- (i) Reliability of the system and MTSF.
- (ii) Pointwise and steady-state availabilities of the system.
- (iii) Expected up time of the system during \mathbf{Q}, t_{\perp} .
- (iv) Expected busy period of the repairman in inspection, in type-I repair,

in type-II repair and in cost repair during Φ, t _.

(v) Net expected profit incurred by the system during Φ , t_{-} and in steady state.

Notations

- N_0 = Unit in *N* (normal) mode and operative.
- F_1 = Unit in *F* (Failure) mode and under inspection.
- F_{r1} = Unit in F-mode and under repair of type-I.
- F_{r^2} = Unit in F-mode and under repair of type-II.
- $F_{\rm Pr}$ = Unit in F-mode and under post repair.
- F_{W1} = Unit in F-mode and waiting for inspection.
- α = Constant failure rate of an operating unit.

Sarita Devi

Deptt. of Mathmatics, Kurukshetra Haryana P = Probability that a failed unit needs type I repair after inspection.

q = Probability that a failed unit needs type II repair after inspection.

 $g_1 \bigcirc g_2 \bigcirc = p.d.f.$ of time to repair of type I and type II.

 $G_1 \bigcirc G_2 \bigcirc$ = C.d.f. of time to repair of type I and type II respectively.

k (K (= p.d.f. and c.d.f. of inspection time of a failed unit.

h, H, H = p.d.f. and c.d.f. of post repair time of a repaired unit. **Model**

The transition diagram along with the possible transitions between the states is shown in fig. 1. The epochs of the entrance from states s_1 to s_4 , s_2 to s_5 s_3 to s_6 and s_7 to s_8 are non-

regenrative.





Fig. 1

The transition probability matrix (t.p.m.) is given by $P = \oint_{ij} = \oint_{ij} = Q$

If the system transits from s_0 to s_1 the

$$Q_{01} \bigoplus_{i=1}^{t} 2\alpha e^{-2\alpha u} du = 1 - e^{-2\alpha}$$
$$Q_{12} \bigoplus_{i=1}^{t} P_{0}^{t} e^{-\alpha u} dK \bigoplus_{i=1}^{t}$$
$$Q_{13} \bigoplus_{i=1}^{t} q_{0}^{t} e^{-\alpha u} dK \bigoplus_{i=1}^{t}$$

$$Q_{14} \bigoplus_{i=1}^{t} \alpha \int_{0}^{t} e^{-\alpha u} \overline{K} \bigoplus_{i=1}^{t} du$$

$$Q_{27} \bigoplus_{i=1}^{t} \int_{0}^{t} e^{-\alpha u} \overline{G}_{1} \bigoplus_{i=1}^{t} du$$

$$Q_{25} \bigoplus_{i=1}^{t} \alpha \int_{0}^{t} e^{-\alpha u} \overline{G}_{1} \bigoplus_{i=1}^{t} du$$

$$Q_{37} \bigoplus_{i=1}^{t} \int_{0}^{t} e^{-\alpha u} \overline{G}_{2} \bigoplus_{i=1}^{t} du$$

$$Q_{45} \bigoplus_{i=1}^{t} \alpha \int_{0}^{t} e^{-\alpha u} \overline{G}_{2} \bigoplus_{i=1}^{t} du$$

$$Q_{45} \bigoplus_{i=1}^{t} \alpha \bigcup_{i=1}^{t} e^{-\alpha u} \overline{G}_{2} \bigoplus_{i=1}^{t} du$$

$$Q_{46} \bigoplus_{i=1}^{t} \alpha \bigcup_{i=1}^{t} \alpha \bigoplus_{i=1}^{t} G_{1} \bigoplus_{i=1}^{t} dG_{2} \bigoplus_{i=1}^{t} G_{2} \bigoplus_{i=1}^{t} dG_{2} \bigoplus_{i=1}^{t} G_{2} \bigoplus_{i=1}^{t} G_{2} \bigoplus_{i=1}^{t} dG_{2} \bigoplus_{i=1}^{t} G_{2} \bigoplus_{i=1}^{t} G_$$

Mean sojourn Time

 m_{ij} as the mean sojourn time by the system in state s_i .

$$m_{ij} = \int t \ Q_{ij} \bigoplus \int t \ q_{ij} \bigoplus dt$$

$$m_{01} = \frac{1}{2\alpha}$$

$$m_{12} = p \int t e^{-\alpha t} \ dK \bigoplus$$

$$m_{13} = q \int t e^{-\alpha t} \ dK \bigoplus$$

$$m_{14} = \alpha \int t e^{-\alpha t} \ \overline{K} \bigoplus dt$$

$$m_{25} = \alpha \int t e^{-\alpha t} \ \overline{G}_{1} \bigoplus dt$$

$$m_{27} = \int t e^{-\alpha t} dG_{1} \langle \zeta \rangle$$

$$m_{37} = \int t e^{-\alpha t} dG_{2} \langle \zeta \rangle$$

$$m_{36} = \alpha \int t e^{-\alpha t} \overline{G}_{2} \langle \zeta \rangle t$$

$$m_{45} = p \int t dK \langle \zeta = P\theta \rangle$$

$$m_{46} = q\theta \qquad m_{58} = n_{1} \qquad m_{68} = n_{2}$$

$$m_{70} = \int t e^{-\alpha t} dH \langle \zeta \rangle$$

$$m_{78} = \alpha \int t e^{-\alpha t} \overline{H} \langle \zeta \rangle t$$

$$m_{81} = m \qquad m_{15}^{0} = p \int t \langle -e^{-\alpha t} \rangle dK \langle \zeta \rangle$$

$$m_{16}^{0} = q \int t \langle -e^{-\alpha t} \rangle dG_{1} \langle \zeta \rangle$$

$$m_{28}^{0} = \int t \langle -e^{-\alpha t} \rangle dG_{2} \langle \zeta \rangle$$

$$m_{71}^{0} = \int t \langle -e^{-\alpha t} \rangle dG_{2} \langle \zeta \rangle$$

$$m_{71}^{0} = \int t \langle -e^{-\alpha t} \rangle dG_{2} \langle \zeta \rangle$$

$$m_{71}^{0} = \int t \langle -e^{-\alpha t} \rangle dH \langle \zeta \rangle$$
Availability analysis
$$A_{0} = \lim_{t \to \infty} A_{0} \langle \zeta \rangle$$

$$= \lim_{s \to 0} s A_{0}^{*} \langle \zeta \rangle$$
Reliability and MISF.
$$R_{0}^{*} \langle \zeta = \frac{N_{1}}{D_{1}} \langle \zeta \rangle$$

$$n_{1} \langle \zeta = z_{0}^{*} + q_{0}^{*} z_{1}^{*} + q_{01}^{*} q_{12}^{*} z_{2}^{*} + q_{01}^{*} q_{13}^{*} z_{3}^{*} + q_{01}^{*}$$

$$m_{12} q_{27}^{*} + q_{13}^{*} q_{37}^{*} z_{7}^{*}$$

$$D_{1} \langle \zeta = 1 - q_{01}^{0} \langle q_{12}^{*} q_{27}^{*} + q_{13}^{*} q_{37}^{*} q_{70}^{*}$$
Busy period analysis of repairman

Let B_i^1 () be the probability that the repairman is busy in inspection of a failed unit at time *t*. B_0^1 () = q_{01} () C_1 () B_1^1 ()

$$B_{1}^{1} \bigoplus \overline{K} \bigoplus q_{12} \bigoplus B_{2}^{1} \bigoplus q_{13} \bigoplus B_{3}^{1} \bigoplus$$
$$+ q_{15}^{\bullet} \bigoplus B_{5}^{1} \bigoplus q_{16}^{\bullet} \bigoplus B_{6}^{1} \bigoplus$$
$$B_{2}^{1} \bigoplus q_{27} \bigoplus B_{5}^{1} \bigoplus q_{16}^{\bullet} \bigoplus B_{6}^{1} \bigoplus$$
$$B_{2}^{1} \bigoplus q_{27} \bigoplus B_{7}^{1} \bigoplus q_{28}^{\bullet} \bigoplus B_{8}^{1} \bigoplus$$
$$B_{3}^{1} \bigoplus q_{37} \bigoplus B_{7}^{1} \bigoplus q_{38}^{\bullet} \bigoplus B_{8}^{1} \bigoplus$$

VOL.-II, ISSUE-IV, OCTOBER-2013

Asian Resonance

$$B_{5}^{1} \bigoplus q_{58} \bigoplus B_{8}^{1} \bigoplus B_{8}^{1} \bigoplus B_{6}^{1} \bigoplus q_{68} \bigoplus B_{8}^{1} \bigoplus B_{6}^{1} \bigoplus q_{68} \bigoplus B_{8}^{1} \bigoplus B_{7}^{1} \bigoplus q_{70} \bigoplus B_{0}^{1} \bigoplus q_{71}^{1} \bigoplus B_{1}^{1} \bigoplus B_{7}^{1} \bigoplus q_{81} \bigoplus B_{1}^{1} \bigoplus B_{1}^$$

- \boldsymbol{K}_2 is the cost of type-I repair per unit of time.
- \boldsymbol{K}_3 is the cost of type-II repair per-unit of time and
- K_4 is the per-unit of time cost of post repair.

$$\mu_{up} = \int_{0}^{t} A_{0} = \int_{0}^{t} A_{0} = \int_{0}^{t} u$$

$$\mu_{b}^{1} = \int_{0}^{t} B_{0}^{1} = \int_{0}^{t} u$$

$$\mu_{b}^{1} = \int_{0}^{t} B_{0}^{1} = \int_{0}^{t} u$$

$$\mu_{b}^{2} = \int_{0}^{t} B_{0}^{2} = \int_{0}^{t} u$$

$$\mu_{b}^{P} = \int_{0}^{t} B_{0}^{P} = \int_{0}^{t} u$$
Then

$$P = K_0 A_0 - K_1 B_0^1 - K_2 B_0^1 - K_3 B_0^2 - K_4 B_0^P$$

Particular Case

All the repair time distribution are also negative exponential.

$$K \bigcirc = 1 - e^{-\eta t}$$

$$G_1 \bigcirc = 1 - e^{-\beta_1 t}$$

$$G_2 \bigcirc = 1 - e^{-\beta_2 t}$$

$$H \bigcirc = 1 - e^{-\mu t}$$
So that

$$\widetilde{K} \bigstar = \frac{\eta}{s+\eta}$$
$$\widetilde{G}_1 \bigstar = \frac{\beta_1}{s+\beta_1}$$

 $\widetilde{G}_2 \bigoplus \frac{\beta_2}{s+\beta_2}$

Then





-40 [⊥]Fig. 3

Conclusion

In fig. 2, we observe that MTSF decreases uniformly as α increases. Moreover, it increases with the increase in η . The similar trends w.r.t. α and η are observed for the case of profit in fig. 3 but here the trends are almost linear.

References

- Balagurusamy, E., Reliability Engineering, Tata Mc Graw 1. Hill Publishing Company Ltd. New Delhi (1984).
- 2 Chung, W.K. 'A K-out of n redundant system with Common Cause Failures' IEEE Trans. Reliab. R-29, 344 (1980)
- Chung, W.K. 'A K-out of n: G Three state unit redundant 3. system with common cause failures and replacements, Microelectron, Reliab, 21, 559-59 (1981).
- Dhillon, B.S. 'A K-out of n-three state devices system with common cause failure'. Micro electron. Reliab, 18, 447-448 (1978). 5.
- Goel, L.R., N.K. Jaiswal and Rakesh Gupta, 'Multistate system with two repair distributions', Microelectron, Reliab., 23(2), 337-340(1983).
- Gujjar, J.S., Reliability Technology Theory and 6. Applications, I K International Publishing House Pvt. Ltd. (2007)
- 7. Medhi, J., Stochastic Process, New Age International New Delhi, (1982) Publishers,
- Mittal, S.K., Gupta, Surbhi. Et al. Analytical Behavior of a 8. Parallel Redundant Complex System Involving Environmental Failure Under had of Line Repair Discipline. Acta Cinecia India. Vol. XXX, II M, No.I. (2006).
- Wang, K.H. A Survey of Maintenance Polices of Deteriorating System. Euro.J.Res. Vol.139(3). (2004).

Fig. 2